

September 21, 2006

Quiz 3

Name: Solution Key

1. Find the values of h for which the set of vectors is linearly dependent: $\left\{ \begin{bmatrix} 2 \\ -4 \\ 1 \end{bmatrix}, \begin{bmatrix} -6 \\ 7 \\ -3 \end{bmatrix}, \begin{bmatrix} 8 \\ h \\ 4 \end{bmatrix} \right\}$
- $$\begin{bmatrix} 2 & -6 & 8 \\ -4 & 7 & h \\ 1 & -3 & 4 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -3 & 4 \\ -4 & 7 & h \\ 1 & -3 & 4 \end{bmatrix} \xrightarrow{\frac{1}{2}R_1} \begin{bmatrix} 1 & -3 & 4 \\ 0 & -5 & 16+h \\ 0 & 0 & 0 \end{bmatrix}$$

The vectors are linearly dependent for any $h \in \mathbb{R}$.

2. Find the standard matrix of a linear transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ that first contracts horizontally by a factor of 0.5 and then reflects points through the line $x_2 = x_1$.

Let $[T] \in \mathbb{R}^{2 \times 2}$ be the matrix of T .

$$[T] = [T(e_1), T(e_2)], \text{ where } e_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, e_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$T(e_1) = \begin{bmatrix} 0 \\ 1/2 \end{bmatrix} \text{ since } \begin{bmatrix} 1 \\ 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1/2 \\ 0 \end{bmatrix} \rightarrow \begin{bmatrix} 0 \\ 1/2 \end{bmatrix}$$

$$T(e_2) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \text{ since } \begin{bmatrix} 0 \\ 1 \end{bmatrix} \rightarrow \begin{bmatrix} 0 \\ 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\text{Thus, } [T] = \begin{bmatrix} 0 & 1 \\ 1/2 & 0 \end{bmatrix}$$

3. The linear transformation $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ is such that $T(e_1) = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$, $T(e_2) = \begin{bmatrix} 2 \\ -4 \end{bmatrix}$, $T(e_3) = \begin{bmatrix} -3 \\ 1 \end{bmatrix}$ where e_i is the i standard basis vector in \mathbb{R}^3 for $i = 1, 2, 3$. Is mapping T onto, one-to-one, or a bijection? Explain.

$$[T] = [T(e_1), T(e_2), T(e_3)] = \begin{bmatrix} 1 & 2 & -3 \\ -2 & -4 & 1 \end{bmatrix}$$

~~T~~ T is not one-to-one since $\# \text{ columns} > \# \text{ rows}$.

T is not a bijection since it is not one-to-one.

$$\begin{bmatrix} 1 & 2 & -3 \\ -2 & -4 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & -3 \\ 0 & 0 & -5 \end{bmatrix}. \text{ There are pivot positions in all rows} \Rightarrow \underline{T \text{ is onto.}}$$