

ORTHOGONAL SPLINE COLLOCATION FOR NONLINEAR DIRICHLET PROBLEMS*

RAKHIM AITBAYEV[†] AND BERNARD BIALECKI[†]

Abstract. We study the orthogonal spline collocation (OSC) solution of a homogeneous Dirichlet boundary value problem in a rectangle for a general nonlinear elliptic partial differential equation. The approximate solution is sought in the space of Hermite bicubic splines. We prove local existence and uniqueness of the OSC solution, obtain optimal order H^1 and H^2 error estimates, and prove the quadratic convergence of Newton's method for solving the OSC problem.

Key words. orthogonal spline collocation, Dirichlet problem, nonlinear, existence, uniqueness, error estimates, Newton's method

AMS subject classifications. 65N35, 65J15, 65N15

PII. S0036142999354538

1. Introduction. The orthogonal spline collocation (OSC) method for the solution of nonlinear one-dimensional boundary value problems (BVPs) was introduced by de Boor and Swartz [6]. An extensive survey of spline collocation methods for solving partial differential equations is given in [5]. In comparison to finite element Galerkin methods, collocation methods do not involve integral approximations in the computation of the coefficients of the resulting algebraic equations. Moreover, the OSC solution has the superconvergence property at the partition nodes [3], [6], [9].

Analyses of the OSC solution of two-dimensional linear BVPs with optimal H^2 and optimal order L^2 and H^1 error estimates were given in [2], [4], [20], [21]. An OSC method with Hermite bicubic splines for the nonlinear equation $\Delta u + F(x, u) = 0$ was studied in [12], where existence and uniqueness of the OSC solution were proved and an optimal order H^1 error estimate obtained under the assumption that the exact solution is in $H^6(\Omega)$. Finite element Galerkin methods for BVPs with nonlinear elliptic equations in divergence form were studied in [10], [11], [19]. Douglas and Dupont [10] considered a mildly nonlinear equation and obtained optimal L^2 and H^1 error estimates. Frehse and Rannacher [11] considered linear finite element approximations for general nonlinear equations and derived “an almost optimal” convergence rate in L^∞ . Park [19] used mixed finite element methods and obtained L^p error estimates for $2 \leq p \leq \infty$.

In this paper, we consider the OSC solution of

$$(1.1) \quad Lu(x) = f(x), \quad x \in \Omega = (0, 1) \times (0, 1), \quad u|_{\partial\Omega} = 0,$$

where $\partial\Omega$ is the boundary of Ω , the nonlinear differential operator

$$(1.2) \quad Lu(x) = \sum_{i,j=1}^2 a_{ij}(x, u, \nabla u) u_{x_i x_j} + a(x, u, \nabla u),$$

*Received by the editors March 31, 1999; accepted for publication (in revised form) July 11, 2000; published electronically November 28, 2000. This work was supported in part by National Science Foundation grant DMS-9805827.

<http://www.siam.org/journals/sinum/38-5/35453.html>

[†]Department of Mathematical and Computer Sciences, Colorado School of Mines, Golden, CO 80401 (aaibaye@mines.edu, bbialeck@mines.edu).

$x = (x_1, x_2)$, and $\nabla u = (u_{x_1}, u_{x_2})$. The OSC scheme consists of finding a Hermite bicubic spline u_h that vanishes on $\partial\Omega$ and satisfies the differential equation of (1.1) at the collocation points. In our analysis, we first obtain the following three basic results: 1) the consistency of the OSC scheme in a discrete norm using the approximation properties of the Hermite bicubic spline interpolant \tilde{u}_h of u [4]; 2) the Lipschitz continuity of the Fréchet derivative of the OSC operator; 3) the uniform boundedness of the inverse of the Fréchet derivative using Bernstein’s transformation [16], a trick similar to that of Nitsche [17], and the Bramble–Hilbert lemma [7]. Then, using the contraction operator principle [15], in a way similar to that in [14], we prove existence and uniqueness of the OSC solution in the ball with center at \tilde{u}_h and radius $\rho = O(|\ln h|^{-(2+q)})$, where $q > 0$ is the exponent in the growth conditions and h is the partition parameter. We obtain H^1 and H^2 error estimates using a generalization of Banach’s theorem [13]. The quadratic convergence of Newton’s method for the solution of the OSC problem is proved in a way similar to that in [22].

An outline of the paper is as follows. In section 2, we give assumptions on L , introduce the notation, and state basic results. In section 3, we formulate the OSC problem and prove a general result concerning this problem. The consistency of the OSC operator is established in section 4. In section 5, we prove the Lipschitz continuity of a Fréchet derivative of the OSC operator. In section 6, we obtain a bound on the inverse of the Fréchet derivative of the OSC operator. The main existence, uniqueness, and error estimate result for the OSC solution is presented in section 7. In section 8, we study the convergence of Newton’s method for the iterative solution of the OSC problem.

2. Preliminaries. Concerning the BVP (1.1), we assume that the functions $a_{ij}(x, s)$ and $a(x, s)$, where $s = (s_0, s_1, s_2)$, are defined on $\bar{\Omega} \times R^3$,

$$(2.1) \quad a_{12}(x, s) = a_{21}(x, s), \quad (x, s) \in \bar{\Omega} \times R^3,$$

and $f(x)$ is continuous on Ω . In the following, the operator L is uniformly elliptic, that is, there is $\nu > 0$ such that

$$(2.2) \quad \sum_{i,j=1}^2 a_{ij}(x, s) \zeta_i \zeta_j \geq \nu (\zeta_1^2 + \zeta_2^2), \quad (\zeta_1, \zeta_2) \in R^2, (x, s) \in \bar{\Omega} \times R^3.$$

Also, for m and $\beta = (\beta_0, \beta_1, \beta_2)$ to be specified later, the functions $a_{ij}(x, s)$ and $a(x, s)$ will have continuous on $\bar{\Omega} \times R^3$ partial derivatives $\partial^{m+|\beta|} a_{ij} / \partial x_l^m \partial s^\beta$ and $\partial^{m+|\beta|} a / \partial x_l^m \partial s^\beta$, respectively, where $|\beta| = \beta_0 + \beta_1 + \beta_2$ and $\partial s^\beta = \partial s_0^{\beta_0} \partial s_1^{\beta_1} \partial s_2^{\beta_2}$. Moreover, we assume that there exists a function $\tilde{\mu}(t_0, t_1, t_2)$ defined for $t_0, t_1, t_2 \geq 0$, which is continuous and nondecreasing in each variable, and such that, for any $(x, s) \in \bar{\Omega} \times R^3$,

$$(2.3a) \quad \left| \frac{\partial^{m+|\beta|} a_{ij}}{\partial x_l^m \partial s^\beta}(x, s) \right| \leq \tilde{\mu}(|s_0|, |s_1|, |s_2|), \quad 1 \leq i, j, l \leq 2,$$

$$(2.3b) \quad \left| \frac{\partial^{m+|\beta|} a}{\partial x_l^m \partial s^\beta}(x, s) \right| \leq \tilde{\mu}(|s_0|, |s_1|, |s_2|), \quad 1 \leq l \leq 2.$$

We set

$$(2.4) \quad \bar{\mu}(t) = \tilde{\mu}(t, t, t), \quad t \geq 0.$$

For convenience, we use the notation $\partial v / \partial x_0 = v_{x_0} = v$. For sufficiently smooth functions y, w , and z defined on Ω , and for $x \in \Omega$, we introduce

$$(2.5) \quad L_y w(x) = \sum_{i,j=1}^2 a_{ij}(x, y, \nabla y) w_{x_i x_j} + \sum_{k=0}^2 A_y^k(x) w_{x_k},$$

$$(2.6) \quad A_y^k(x) = \sum_{i,j=1}^2 \frac{\partial a_{ij}}{\partial s_k}(x, y, \nabla y) y_{x_i x_j} + \frac{\partial a}{\partial s_k}(x, y, \nabla y), \quad k = 0, 1, 2.$$

The differential operator L_y can be viewed as a formal first derivative of L at y . If the functions y and w are twice differentiable at $x \in \Omega$, then

$$(2.7) \quad L(y + w)(x) - Ly(x) = \int_0^1 L_{y+tw} w(x) dt$$

(see [1, Lemma 4.1]).

For positive integers N_1 and N_2 , let $\pi_i = \{x_i^k\}_{k=0}^{N_i}, i = 1, 2$, be a nonuniform partition of the interval $[0, 1]$. We set $h_i^k = x_i^k - x_i^{k-1}, k = 1, \dots, N_i, i = 1, 2$, and introduce $\underline{h}_i = \min_k h_i^k, \bar{h}_i = \max_k h_i^k$, and $h = \max\{\bar{h}_1, \bar{h}_2\}$. Let π_h be the partition of Ω associated with the grid $\pi_1 \times \pi_2$. We consider a regular collection of partitions π_h , that is, we assume that there exist positive constants σ_1, σ_2 , and σ_3 , all independent of h , such that $\sigma_1 \leq \bar{h}_1 / \bar{h}_2 \leq \sigma_2$ and $\underline{h}_i / \bar{h}_i \geq \sigma_3$ for $i = 1, 2$. Let \mathcal{T}_h be the set of all open rectangles generated by the partition π_h , that is,

$$\mathcal{T}_h = \{\tau = (x_1^{k_1-1}, x_1^{k_1}) \times (x_2^{k_2-1}, x_2^{k_2}) : 1 \leq k_i \leq N_i, i = 1, 2\}.$$

The set of Gauss points in Ω corresponding to the partition π_h is defined by

$$\mathcal{G}_h = \{(\xi_1^{m_1}, \xi_2^{m_2}) : 1 \leq m_i \leq 2N_i, i = 1, 2\},$$

where $\xi_i^{2k_i-1} = x_i^{k_i-1} + h_i^{k_i} \eta_1, \xi_i^{2k_i} = x_i^{k_i-1} + h_i^{k_i} \eta_2, 1 \leq k_i \leq N_i, i = 1, 2$, and

$$(2.8) \quad \eta_1 = (3 - \sqrt{3})/6, \quad \eta_2 = (3 + \sqrt{3})/6.$$

For any v defined on \mathcal{G}_h , let

$$\sum_h v = \frac{1}{4} \sum_{\tau \in \mathcal{T}_h} \text{mes}(\tau) \sum_{\xi \in \mathcal{G}_h \cap \tau} v(\xi), \quad \|v\|_h^2 = \sum_h v^2.$$

For $E \subset R^2$, let $\|\cdot\|_{L^2(E)}, \|\cdot\|_{H^l(E)}$, and $\|\cdot\|_{C^l(E)}$ for integer $l \geq 0$ denote the standard norms in the indicated spaces.

We introduce the “broken” C^2 -space

$$C^2(\mathcal{T}_h) = \{v \in L^2(\Omega) : v|_\tau \in C^2(\tau), \tau \in \mathcal{T}_h\}$$

and set $\|v\|_{C^2(\mathcal{T}_h)} = \max_{\tau \in \mathcal{T}_h} \|v\|_{C^2(\tau)}$ for any $v \in C^2(\mathcal{T}_h)$. Let \mathcal{P}_h be the set of all piecewise bicubic polynomial functions defined on \mathcal{T}_h , that is, $\mathcal{P}_h = \{v : v|_\tau \in P_3 \otimes P_3, \tau \in \mathcal{T}_h\}$, where P_3 is the set of all polynomials of degree ≤ 3 , and the symbol \otimes denotes the tensor product. For the partition π_h , let \mathcal{M}_h^0 be the space of Hermite bicubic splines vanishing on $\partial\Omega$. We note that $\|\cdot\|_h$ is a norm in \mathcal{M}_h^0 since any element of \mathcal{M}_h^0 is uniquely determined by its values on \mathcal{G}_h [20, Lemma 5.1].

Throughout this paper, C denotes a generic positive constant independent of h ; the value of C may be different each time it is written. For $\alpha = (\alpha_1, \alpha_2)$, let $|\alpha| = \alpha_1 + \alpha_2$ and $\partial^\alpha = \partial^{\alpha_1 + \alpha_2} / (\partial x_1^{\alpha_1} \partial x_2^{\alpha_2})$. For any $v \in C^2(\bar{\Omega})$ and partition π_h , $\tilde{v}_h \in \mathcal{M}_h$ denotes the Hermite bicubic spline interpolant of v .

LEMMA 2.1. For $v \in H^4(\Omega)$ and $l = 0, 1, 2$,

$$(2.9) \quad \|\tilde{v}_h\|_{C^2(\mathcal{T}_h)} \leq C \|v\|_{H^4(\Omega)},$$

$$(2.10) \quad \|v - \tilde{v}_h\|_{H^l(\Omega)} \leq C h^{4-l} \|v\|_{H^4(\Omega)},$$

$$(2.11) \quad \sum_{|\alpha|=l} \|\partial^\alpha(v - \tilde{v}_h)\|_h \leq C h^{4-l} \|v\|_{H^4(\Omega)},$$

and, for $v \in H^5(\Omega)$,

$$(2.12) \quad \sum_{|\alpha|=2} \|\partial^\alpha(v - \tilde{v}_h)\|_h \leq C h^3 \|v\|_{H^5(\Omega)}.$$

Proof. From [8, Theorem 3.1.6], we have $\|v - \tilde{v}_h\|_{C^2(\tau)} \leq Ch \|v\|_{H^4(\tau)}$, $\tau \in \mathcal{T}_h$. Hence (2.9) follows from the triangle inequality for $\|\cdot\|_{C^2(\tau)}$ and the inequality $\|v\|_{C^2(\bar{\Omega})} \leq C \|v\|_{H^4(\Omega)}$. Inequalities (2.10) and (2.11), (2.12) are proved in [8, Theorem 3.2.1] and [4, Lemma 4.2], respectively. \square

If a function $G(x, t)$ defined on $\mathcal{G}_h \times [0, 1]$ is continuous in t for all $x \in \mathcal{G}_h$, then

$$(2.13) \quad \left\| \int_0^1 G(\cdot, t) dt \right\|_h \leq \int_0^1 \|G(\cdot, t)\|_h dt$$

(see [18, Lemma 3.2.11]).

3. The OSC problem and a general result. We define the OSC operator L_h from \mathcal{M}_h^0 into \mathcal{M}_h^0 and $f_h \in \mathcal{M}_h^0$ by

$$(3.1) \quad L_h v_h(x) = Lv_h(x), \quad x \in \mathcal{G}_h,$$

$$(3.2) \quad f_h(x) = f(x), \quad x \in \mathcal{G}_h.$$

The OSC problem is formulated as follows: find $u_h \in \mathcal{M}_h^0$ such that

$$(3.3) \quad L_h u_h = f_h.$$

Hereafter, L_h is viewed as an operator from \mathcal{M}_h^0 with the H^2 -norm into \mathcal{M}_h^0 with the norm $\|\cdot\|_h$, and $L_{h,y}$ denotes the Fréchet derivative of L_h at $y \in \mathcal{M}_h^0$. Also, $\|L_{h,y}\|$ and $\|L_{h,y}^{-1}\|$ are the corresponding operator norms of $L_{h,y}$ and $L_{h,y}^{-1}$, respectively.

For $z \in \mathcal{M}_h^0$ and $\rho \geq 0$, let $B_h(z, \rho) = \{w \in \mathcal{M}_h^0 : \|w - z\|_{H^2(\Omega)} \leq \rho\}$. We prove the following general existence, uniqueness, and error estimate result for the OSC problem (3.3) (cf. [14, Theorems 2.6 and 3.6]).

THEOREM 3.1. Let $u \in C^2(\bar{\Omega})$ be a solution of problem (1.1), and suppose that, for some h and some $\rho > 0$, $L_{h,y}$ exists for all $y \in B_h(\tilde{u}_h, \rho)$, L_{h,\tilde{u}_h}^{-1} exists, and

$$(3.4) \quad \|L_{h,\tilde{u}_h}^{-1}\| \leq K_1,$$

$$(3.5) \quad \|L_{h,z} - L_{h,y}\| \leq K_2 \|z - y\|_{H^2(\Omega)}, \quad y, z \in B_h(\tilde{u}_h, \rho),$$

$$(3.6) \quad \|Lu - L_h \tilde{u}_h\|_h \leq K_3 h^p,$$

$$(3.7) \quad \rho K_1 K_2 \leq 1/2,$$

$$(3.8) \quad K_1 K_3 h^p \leq \rho/2,$$

where positive K_1 and nonnegative K_2, K_3 , and p are constants. Then (3.3) has a unique solution $u_h \in B_h(\tilde{u}_h, \rho)$, and

$$(3.9) \quad \|u_h - \tilde{u}_h\|_{H^2(\Omega)} \leq 2K_1 K_3 h^p.$$

Proof. First we prove existence and uniqueness of the OSC solution. Since $B_h(\tilde{u}_h, \rho)$ is a convex set, it follows that

$$(3.10) \quad y + t(z - y) \in B_h(\tilde{u}_h, \rho), \quad t \in [0, 1], \quad y, z \in B_h(\tilde{u}_h, \rho).$$

Using (3.10) and the existence of $L_{h,y}, y \in B_h(\tilde{u}_h, \rho)$, we conclude that $L_{h,y+t(z-y)}$ is defined for all $t \in [0, 1]$ and for all $y, z \in B_h(\tilde{u}_h, \rho)$. By (3.5), for any $y, z \in B_h(\tilde{u}_h, \rho)$, we obtain

$$\|L_{h,y+t_1(z-y)} - L_{h,y+t_2(z-y)}\| \leq K_2 \|z - y\|_{H^2(\Omega)} |t_1 - t_2|, \quad t_1, t_2 \in [0, 1],$$

which implies continuity of the mapping that assigns $L_{h,y+t(z-y)}$ to each $t \in [0, 1]$. Hence, for any $y, z \in B_h(\tilde{u}_h, \rho)$ and any $w \in \mathcal{M}_h^0$, $L_{h,y+t(z-y)} w$ is continuous as a mapping of $t \in [0, 1]$ into \mathcal{M}_h^0 .

Using (2.13), (3.5), and (3.10), for any $y, z \in B_h(\tilde{u}_h, \rho)$ and any $w \in \mathcal{M}_h^0$, we obtain

$$(3.11) \quad \left\| \int_0^1 [L_{h,\tilde{u}_h} - L_{h,y+t(z-y)}] w dt \right\|_h \leq \int_0^1 \|[L_{h,\tilde{u}_h} - L_{h,y+t(z-y)}] w\|_h dt \\ \leq \int_0^1 \|L_{h,\tilde{u}_h} - L_{h,y+t(z-y)}\| \|w\|_{H^2(\Omega)} dt \leq \rho K_2 \|w\|_{H^2(\Omega)}.$$

It follows from a result in [13, Chapter XVII, section 1.7] that

$$(3.12) \quad L_h z - L_h y = \int_0^1 L_{h,y+t(z-y)} (z - y) dt, \quad y, z \in B_h(\tilde{u}_h, \rho).$$

Let G_h be an operator from \mathcal{M}_h^0 into \mathcal{M}_h^0 defined by

$$(3.13) \quad G_h v = v - L_{h,\tilde{u}_h}^{-1} (L_h v - f_h), \quad v \in \mathcal{M}_h^0.$$

Using (3.13) and (3.12), for any $y, z \in B_h(\tilde{u}_h, \rho)$, we get

$$\|G_h z - G_h y\|_{H^2(\Omega)} = \left\| z - y - L_{h,\tilde{u}_h}^{-1} (L_h z - L_h y) \right\|_{H^2(\Omega)} \\ \leq \left\| L_{h,\tilde{u}_h}^{-1} \right\| \left\| \int_0^1 [L_{h,\tilde{u}_h} - L_{h,y+t(z-y)}] (z - y) dt \right\|_h.$$

Thus (3.4), (3.11) with $w = z - y$, and (3.7) give

$$(3.14) \quad \|G_h z - G_h y\|_{H^2(\Omega)} \leq (1/2) \|z - y\|_{H^2(\Omega)}, \quad y, z \in B_h(\tilde{u}_h, \rho).$$

Using (3.13), (3.4), (3.2), (1.1), (3.6), and (3.8), we obtain

$$(3.15) \quad \|\tilde{u}_h - G_h \tilde{u}_h\|_{H^2(\Omega)} = \left\| L_{h,\tilde{u}_h}^{-1} (L_h \tilde{u}_h - f_h) \right\|_{H^2(\Omega)} \leq \left\| L_{h,\tilde{u}_h}^{-1} \right\| \|L_h \tilde{u}_h - f_h\|_h \\ \leq K_1 \|L_h \tilde{u}_h - Lu\|_h \leq K_1 K_3 h^p \leq \rho/2.$$

From (3.14), (3.15), and the contraction operator principle [15, Theorem 1.2], we conclude that there is a unique $u_h \in B_h(\tilde{u}_h, \rho)$ such that $G_h u_h = u_h$, which, by (3.13), shows that (3.3) has a unique solution $u_h \in B_h(\tilde{u}_h, \rho)$.

We now prove the estimate (3.9). We fix $y, z \in B_h(\tilde{u}_h, \rho)$ and view $L_h(y, z)$, defined by

$$(3.16) \quad L_h(y, z) w \equiv \int_0^1 L_{h,y+t(z-y)} w dt, \quad w \in \mathcal{M}_h^0,$$

as a linear operator from \mathcal{M}_h^0 with the H^2 -norm into \mathcal{M}_h^0 with the norm $\|\cdot\|_h$.

Using (3.16) and (3.11), we obtain

$$\|[L_{h,\tilde{u}_h} - L_h(y, z)] w\|_h = \left\| \int_0^1 [L_{h,\tilde{u}_h} - L_{h,y+t(z-y)}] w dt \right\|_h \leq \rho K_2 \|w\|_{H^2(\Omega)}$$

for any $w \in \mathcal{M}_h^0$, which implies

$$(3.17) \quad \|L_h(y, z) - L_{h,\tilde{u}_h}\| \leq \rho K_2.$$

From (3.17), (3.7), and (3.4), we have

$$\|L_h(y, z) - L_{h,\tilde{u}_h}\| \leq \rho K_1 K_2 K_1^{-1} \leq (2 K_1)^{-1} < \|L_{h,\tilde{u}_h}^{-1}\|^{-1}.$$

Hence, using the existence of L_{h,\tilde{u}_h}^{-1} , (3.4), and the generalization of Banach's theorem on the existence of an inverse operator [13, Chapter V, section 4, Theorem 4], we conclude that $L_h(y, z)$ has an inverse and, by (3.4), (3.17), and (3.7),

$$(3.18) \quad \|[L_h(y, z)]^{-1}\| \leq \|L_{h,\tilde{u}_h}^{-1}\| \left(1 - \|L_{h,\tilde{u}_h}^{-1}\| \|L_h(y, z) - L_{h,\tilde{u}_h}\|\right)^{-1} \leq 2 K_1.$$

Inequality (3.18) is equivalent to

$$(3.19) \quad \|w\|_{H^2(\Omega)} \leq 2 K_1 \|L_h(y, z) w\|_h, \quad w \in \mathcal{M}_h^0.$$

Setting $w = z - y$ in (3.19) and using (3.16) and (3.12), we obtain

$$(3.20) \quad \|z - y\|_{H^2(\Omega)} \leq 2 K_1 \|L_h z - L_h y\|_h, \quad y, z \in B_h(\tilde{u}_h, \rho).$$

Finally, setting $y = \tilde{u}_h$ and $z = u_h$ in (3.20), and using (3.3), (3.2), (1.1), and (3.6), we obtain (3.9). \square

Inequality (3.5) is called the Lipschitz continuity of a Fréchet derivative of L_h in $B_h(\tilde{u}_h, \rho)$ with the Lipschitz constant K_2 . If p and K_3 are independent of h , then the inequality (3.6) is called the consistency of the OSC operator L_h at u .

4. Consistency. In this section, we prove the consistency of the operator L_h .

LEMMA 4.1. *Suppose that (2.3a) and (2.3b) hold for all β with $|\beta| \leq 1$ and $|\beta| = 1$, respectively, and for $m = 0$. Then*

$$(4.1) \quad \|Lv - L_h \tilde{v}_h\|_h \leq K_3 h^{k-2}, \quad v \in H^k(\Omega), \quad k = 4, 5,$$

where K_3 is independent of h but depends on $\|v\|_{H^k(\Omega)}$.

Proof. If $v \in H^4(\Omega)$, then $v \in C^2(\bar{\Omega})$. Using (3.1) and (2.7) with $y = \tilde{v}_h$ and $w = v - \tilde{v}_h$, we have

$$(4.2) \quad Lv(x) - L_h \tilde{v}_h(x) = Lv(x) - L\tilde{v}_h(x) = \int_0^1 L_{y_h(t)}(v - \tilde{v}_h)(x) dt, \quad x \in \mathcal{G}_h,$$

where $y_h(t) = \tilde{v}_h + t(v - \tilde{v}_h)$. Using (2.5), (2.6) and the smoothness of a_{ij} , $1 \leq i, j \leq 2$, and a , it is easy to verify that, for any $x \in \mathcal{G}_h$, $L_{y_h(t)}(v - \tilde{v}_h)(x)$ is continuous for $t \in [0, 1]$. Hence, (4.2) and (2.13) imply that

$$(4.3) \quad \|Lv - L_h \tilde{v}_h\|_h \leq \int_0^1 \|L_{y_h(t)}(v - \tilde{v}_h)\|_h dt.$$

With $\bar{\mu}$ defined by (2.4), the inequality

$$\begin{aligned} |L_{y_h(t)}(v - \tilde{v}_h)(x)| &\leq \bar{\mu} \left(\|y_h(t)\|_{C^1(\bar{\Omega})} \right) (1 + \|y_h(t)\|_{C^2(\mathcal{T}_h)}) \\ &\quad \times \sum_{|\alpha| \leq 2} |\partial^\alpha (v - \tilde{v}_h)(x)|, \quad x \in \mathcal{T}_h \end{aligned}$$

(see [1, Lemma 4.2, (ii)]), and the triangle inequality for $\|\cdot\|_h$ give

$$(4.4) \quad \|L_{y_h(t)}(v - \tilde{v}_h)\|_h \leq \bar{\mu} \left(\|y_h(t)\|_{C^1(\bar{\Omega})} \right) (1 + \|y_h(t)\|_{C^2(\mathcal{T}_h)}) W, \quad t \in [0, 1],$$

where $W = \sum_{|\alpha| \leq 2} \|\partial^\alpha (v - \tilde{v}_h)\|_h$. Using (2.11), we have

$$(4.5) \quad W \leq Ch^2 \|v\|_{H^4(\Omega)}.$$

Since $v, \tilde{v}_h \in C^2(\mathcal{T}_h)$, on applying the triangle inequality for $\|\cdot\|_{C^2(\mathcal{T}_h)}$, the inequality $\|v\|_{C^2(\bar{\Omega})} \leq C\|v\|_{H^4(\Omega)}$, and (2.9), we have

$$(4.6) \quad \|y_h(t)\|_{C^2(\mathcal{T}_h)} \leq C\|v\|_{H^4(\Omega)}, \quad t \in [0, 1].$$

Hence, from (4.4), (4.5), and (4.6), we obtain

$$\|L_{y_h(t)}(v - \tilde{v}_h)\|_h \leq C\|v\|_{H^4(\Omega)} \bar{\mu}(C\|v\|_{H^4(\Omega)}) (1 + \|v\|_{H^4(\Omega)}) h^2, \quad t \in [0, 1],$$

which, along with (4.3), gives (4.1) for $k = 4$.

If $v \in H^5(\Omega)$, then (2.11) for $l = 0, 1$, and (2.12) imply $W \leq Ch^3 \|v\|_{H^5(\Omega)}$ which gives (4.1) for $k = 5$. \square

5. Lipschitz continuity of a Fréchet derivative. Let $L_y w(x)$ be given by (2.5) and (2.6), and let

$$(5.1) \quad \lambda_{y,z} = \|y\|_{H^2(\Omega)} + \|z\|_{H^2(\Omega)}, \quad y, z \in H^2(\Omega).$$

LEMMA 5.1. *Suppose that $h \in (0, e^{-2}]$ and that (2.3a) and (2.3b) hold for all β with $|\beta| = 1, 2$ and $|\beta| = 2$, respectively, and $m = 0$. Then L_h has a Fréchet derivative $L_{h,y}$ for each $y \in \mathcal{M}_h^0$, and*

$$(5.2) \quad L_{h,y} w(x) = L_y w(x), \quad x \in \mathcal{G}_h, \quad w \in \mathcal{M}_h^0.$$

Moreover, for any $v \in H^4(\Omega)$ and any $\rho_0 > 0$,

$$(5.3) \quad \|L_{h,z} - L_{h,y}\| \leq K_2(h, \rho_0, v) \|z - y\|_{H^2(\Omega)}, \quad y, z \in B_h(\tilde{v}_h, \rho_0),$$

where

$$(5.4) \quad K_2(h, \rho_0, v) \equiv (\ln^2 h) (C + \gamma) \tilde{\mu}(\gamma, |\ln h| \gamma, |\ln h| \gamma),$$

and $\gamma = C(\|v\|_{H^4(\Omega)} + \rho_0)$.

Proof. We take any y and $w \neq 0$ in \mathcal{M}_h^0 . Using (2.7), we have

$$(5.5) \quad \|L(y+w) - Ly - L_y w\|_h = \left\| \int_0^1 (L_{y+tw} - L_y) w \, dt \right\|_h.$$

Since the functions a_{ij} and a are sufficiently smooth, $L_{y+tw} w(x)$ is continuous in $t \in [0, 1]$ for all $x \in \mathcal{G}_h$. Using (2.13) with $G(x, t) = (L_{y+tw} w - L_y w)(x)$, we obtain

$$(5.6) \quad \left\| \int_0^1 (L_{y+tw} - L_y) w \, dt \right\|_h \leq \int_0^1 \|(L_{y+tw} - L_y) w\|_h \, dt.$$

In [1, Lemma 6.1], we proved that, for $h \in (0, e^{-2}]$,

$$(5.7) \quad \|(L_{y+z} - L_y) w\|_h \leq \Psi_h[y, z] \|z\|_{H^2(\Omega)} \|w\|_{H^2(\Omega)}, \quad z \in \mathcal{M}_h^0,$$

where

$$(5.8) \quad \Psi_h[y, z] = C(\ln^2 h) \tilde{\mu}(C\lambda_{y,z}, C|\ln h|\lambda_{y,z}, C|\ln h|\lambda_{y,z})(1 + \lambda_{y,z}),$$

and $\lambda_{y,z}$ is given by (5.1). Applying (5.7) with $z = tw$ and the inequality $\Psi_h[y, tw] \leq \Psi_h[y, w]$, $t \in [0, 1]$, we get

$$(5.9) \quad \begin{aligned} \int_0^1 \|(L_{y+tw} - L_y) w\|_h \, dt &\leq \int_0^1 t \Psi_h[y, tw] \|w\|_{H^2(\Omega)}^2 \, dt \\ &\leq (1/2) \Psi_h[y, w] \|w\|_{H^2(\Omega)}^2. \end{aligned}$$

From (5.5), (5.6), and (5.9), it follows that

$$(5.10) \quad \|L(y+w) - Ly - L_y w\|_h \leq (1/2) \Psi_h[y, w] \|w\|_{H^2(\Omega)}^2.$$

We define the linear operator $L_{y,h}$ from \mathcal{M}_h^0 into \mathcal{M}_h^0 by

$$(5.11) \quad L_{y,h} z(x) = L_y z(x), \quad x \in \mathcal{G}_h.$$

Using (5.10), (3.1), and (5.11), we obtain

$$(5.12) \quad \|L_h(y+w) - L_h y - L_{y,h} w\|_h / \|w\|_{H^2(\Omega)} \leq (1/2) \Psi_h[y, w] \|w\|_{H^2(\Omega)}.$$

Since $\tilde{\mu}$ is nondecreasing, it follows from (5.8) and (5.1) that $\Psi_h[y, w] \|w\|_{H^2(\Omega)} \rightarrow 0$ as $\|w\|_{H^2(\Omega)} \rightarrow 0$. The operator $L_{y,h}$ is bounded since it is linear and \mathcal{M}_h^0 is finite dimensional. Therefore, (5.12) implies that $L_{y,h}$ is a Fréchet derivative of L_h at y . Hence (5.2) follows from (5.11).

To prove (5.3), we take any $v \in H^4(\Omega)$, any $\rho_0 > 0$, and any $y, z \in B_h(\tilde{v}_h, \rho_0)$. Using (5.7) with z replaced by $z - y$, we have

$$(5.13) \quad \|(L_z - L_y) w\|_h \leq \Psi_h[y, z - y] \|z - y\|_{H^2(\Omega)} \|w\|_{H^2(\Omega)}, \quad w \in \mathcal{M}_h^0.$$

Since $y, z \in B_h(\tilde{v}_h, \rho_0)$, using the triangle inequality and (2.9), we have

$$(5.14) \quad \|y\|_{H^2(\Omega)} \leq \|\tilde{v}_h\|_{H^2(\Omega)} + \|y - \tilde{v}_h\|_{H^2(\Omega)} \leq C \|\tilde{v}_h\|_{C^2(\mathcal{I}_h)} + \rho_0 \leq C \|v\|_{H^4(\Omega)} + \rho_0$$

and

$$(5.15) \quad \|z - y\|_{H^2(\Omega)} \leq \|z - \tilde{v}_h\|_{H^2(\Omega)} + \|y - \tilde{v}_h\|_{H^2(\Omega)} \leq 2\rho_0.$$

Using (5.1), (5.14), (5.15), and the definition of γ , we obtain $\lambda_{y,z-y} \leq \gamma$. Therefore, from (5.8), we have

$$(5.16) \quad \Psi_h [y, z - y] \leq (\ln^2 h)(C + \gamma) \tilde{\mu}(\gamma, |\ln h| \gamma, |\ln h| \gamma).$$

From (5.13) and (5.16), we get (5.3) and (5.4). \square

The Lipschitz constant $K_2(h, \rho_0, v)$ in (5.4) is independent of h if the coefficients a_{ij} of the differential operator L do not depend on ∇u (see [1, Lemma 6.4]).

6. Bound on the inverse of the Fréchet derivative. In this section, we prove that, if $v \in H^4(\Omega)$, then L_{h,\tilde{v}_h}^{-1} exists and its norm is uniformly bounded for h sufficiently small. This result follows from the two auxiliary inequalities obtained in the following two subsections. Throughout this section, $\lambda_v = \|v\|_{H^4(\Omega)}$ for $v \in H^4(\Omega)$.

6.1. First auxiliary inequality. The first auxiliary inequality is given in the following lemma.

LEMMA 6.1. *Suppose that (2.3a) holds for $m = 0$ and all β such that $|\beta| \leq 1$, and that (2.3b) holds for $m = 0$ and all β such that $|\beta| = 1$. If $v \in H^4(\Omega)$, then, for any $w \in \mathcal{M}_h^0$,*

$$(6.1) \quad \|w\|_{H^2(\Omega)} \leq C \nu^{-2} \bar{\mu}(C\lambda_v) \|L_{h,\tilde{v}_h} w\|_h + C \nu^{-4} \bar{\mu}^4(C\lambda_v) (1 + \lambda_v)^2 \|w\|_{L^2(\Omega)}.$$

Proof. The proof is similar to that of Lemma 3.1 in [2], and it involves the application of Bernstein’s transformation [16, p. 452]. For $x \in \mathcal{G}_h$, we introduce

$$(6.2) \quad b_{ij}(x) = a_{ij}(x, \tilde{v}_h(x), \nabla \tilde{v}_h(x)), \quad i, j = 1, 2,$$

$$(6.3) \quad b_k(x) = A_{\tilde{v}_h}^k(x), \quad k = 0, 1, 2,$$

where $A_{\tilde{v}_h}^k$ is given by (2.6). For any $w \in \mathcal{M}_h^0$ and $x \in \mathcal{G}_h$, (2.5), (6.2), and (6.3) imply that

$$(6.4) \quad \sum_{i,j=1}^2 b_{ij} w_{x_i x_j} = L_{\tilde{v}_h} w - \sum_{k=0}^2 b_k w_{x_k} \equiv \Phi,$$

where b_{ij} , b_k , Φ , w and its derivatives are evaluated at x .

First, using (6.4), we bound

$$(6.5) \quad |w|_{2,h} \equiv (\|w_{x_1 x_1}\|_h^2 + 2 \|w_{x_1 x_2}\|_h^2 + \|w_{x_2 x_2}\|_h^2)^{1/2}$$

in terms of $\|\Phi\|_h$. Inequality (2.2) with $(\zeta_1, \zeta_2) = (1, 0)$ and $(\zeta_1, \zeta_2) = (0, 1)$ implies that $b_{ii} \geq \nu > 0$, $i = 1, 2$. Therefore, multiplying (6.4) by $b_{22}^{-1} w_{x_1 x_1} + b_{11}^{-1} w_{x_2 x_2}$, we obtain

$$(6.6) \quad I \equiv \sum_{i,j=1}^2 b_{ij} w_{x_i x_j} (b_{22}^{-1} w_{x_1 x_1} + b_{11}^{-1} w_{x_2 x_2}) = \Phi(x) (b_{22}^{-1} w_{x_1 x_1} + b_{11}^{-1} w_{x_2 x_2}).$$

Since (6.2) and (2.1) imply $b_{12} = b_{21}$, (6.6) gives

$$(6.7) \quad I = 2 (w_{x_1 x_1} w_{x_2 x_2} - w_{x_1 x_2}^2) + b_{22}^{-1} (b_{11} w_{x_1 x_1}^2 + 2 b_{12} w_{x_1 x_1} w_{x_1 x_2} + b_{22} w_{x_1 x_2}^2) + b_{11}^{-1} (b_{11} w_{x_1 x_2}^2 + 2 b_{12} w_{x_1 x_2} w_{x_2 x_2} + b_{22} w_{x_2 x_2}^2).$$

It follows easily from (6.2) and (2.2) that

$$(6.8) \quad \sum_{i,j=1}^2 b_{ij} \zeta_i \zeta_j \geq \nu (\zeta_1^2 + \zeta_2^2), \quad (\zeta_1, \zeta_2) \in R^2.$$

Equations (6.7) and (6.8) applied twice give

$$(6.9) \quad I \geq \nu b_{22}^{-1} (w_{x_1 x_1}^2 + w_{x_1 x_2}^2) + \nu b_{11}^{-1} (w_{x_1 x_2}^2 + w_{x_2 x_2}^2) + 2 (w_{x_1 x_1} w_{x_2 x_2} - w_{x_1 x_2}^2).$$

Using (6.2), (2.3a) with $m = 0$ and $|\beta| = 0$, (2.4), and (2.9), we obtain

$$(6.10) \quad b_{ii} \leq \tilde{\mu} (|\tilde{v}_h(x)|, |(\tilde{v}_h)_{x_1}(x)|, |(\tilde{v}_h)_{x_2}(x)|) \leq \bar{\mu} (\|\tilde{v}_h\|_{C^1(\bar{\Omega})}) \leq \mu_v, \quad i = 1, 2,$$

where $\mu_v \equiv \bar{\mu}(C\lambda_v)$. Therefore, from (6.9) and (6.10), we have

$$(6.11) \quad I \geq \nu \mu_v^{-1} (w_{x_1 x_1}^2 + 2 w_{x_1 x_2}^2 + w_{x_2 x_2}^2) + 2 (w_{x_1 x_1} w_{x_2 x_2} - w_{x_1 x_2}^2).$$

Using (6.11), (6.6), and $b_{ii} \geq \nu$, we have

$$(6.12) \quad \nu^{-1} |\Phi| (|w_{x_1 x_1}| + |w_{x_2 x_2}|) \geq \nu \mu_v^{-1} (w_{x_1 x_1}^2 + 2 w_{x_1 x_2}^2 + w_{x_2 x_2}^2) + 2 (w_{x_1 x_1} w_{x_2 x_2} - w_{x_1 x_2}^2).$$

Multiplying (6.12) by the Gaussian quadrature weights and summing over all $x \in \mathcal{G}_h$, we obtain

$$(6.13) \quad \nu \mu_v^{-1} |w|_{2,h}^2 + 2 \sum_h (w_{x_1 x_1} w_{x_2 x_2} - w_{x_1 x_2}^2) \leq \nu^{-1} \sum_h |\Phi| (|w_{x_1 x_1}| + |w_{x_2 x_2}|),$$

where $|w|_{2,h}$ is defined in (6.5). It easily follows from (6.5) that

$$(6.14) \quad \|w_{x_1 x_1}\|_h^2 + \|w_{x_2 x_2}\|_h^2 \leq |w|_{2,h}^2.$$

The Cauchy–Schwarz inequality in R^2 and (6.14) give

$$(6.15) \quad \|w_{x_1 x_1}\|_h + \|w_{x_2 x_2}\|_h \leq \sqrt{2} (\|w_{x_1 x_1}\|_h^2 + \|w_{x_2 x_2}\|_h^2)^{1/2} \leq \sqrt{2} |w|_{2,h}.$$

The Cauchy–Schwarz inequality in \mathcal{M}_h^0 and (6.15) imply

$$(6.16) \quad \sum_h |\Phi| (|w_{x_1 x_1}| + |w_{x_2 x_2}|) \leq \sqrt{2} \|\Phi\|_h |w|_{2,h}.$$

Using (6.13), the inequality

$$\sum_h z_{x_1 x_1} z_{x_2 x_2} - \sum_h z_{x_1 x_2}^2 \geq 0, \quad z \in \mathcal{M}_h^0,$$

which is (2.5) in [2], and (6.16), we obtain

$$(6.17) \quad |w|_{2,h} \leq \sqrt{2} \nu^{-2} \mu_v \|\Phi\|_h.$$

Next we bound $\|\Phi\|_h$. Using (6.4) and the triangle inequality, we obtain

$$(6.18) \quad \|\Phi\|_h \leq \|L_{\tilde{v}_h} w\|_h + \left(\max_{k=0,1,2} \max_{x \in \mathcal{G}_h} |b_k(x)| \right) \sum_{k=0}^2 \|w_{x_k}\|_h.$$

Since $\mathcal{M}_h^0 \subset C^2(\mathcal{T}_h)$, (6.3), (2.4), and the inequality

$$|A_{\tilde{v}_h}^k(x)| \leq \bar{\mu} \left(\|\tilde{v}_h\|_{C^1(\bar{\Omega})} \right) \left(1 + \|\tilde{v}_h\|_{C^2(\mathcal{T}_h)} \right), \quad x \in \mathcal{G}_h, \quad k = 0, 1, 2$$

(see [1, Lemma 4.2, (i)]) give

$$\max_{x \in \mathcal{G}_h} |b_k(x)| \leq \bar{\mu} \left(\|\tilde{v}_h\|_{C^1(\bar{\Omega})} \right) \left(1 + \|\tilde{v}_h\|_{C^2(\mathcal{T}_h)} \right), \quad k = 0, 1, 2.$$

Hence, from (2.9), we have

$$(6.19) \quad \max_{k=0,1,2} \max_{x \in \mathcal{G}_h} |b_k(x)| \leq C \mu_v (1 + \lambda_v).$$

Using Cauchy–Schwarz’s inequality in R^2 , the inequality

$$\|z_{x_1}\|_h^2 + \|z_{x_2}\|_h^2 \leq - \sum_h (\Delta z) z, \quad z \in \mathcal{M}_h^0,$$

which is (2.6) in [2], and the Cauchy–Schwarz inequality in \mathcal{M}_h^0 , we obtain

$$\|w_{x_1}\|_h + \|w_{x_2}\|_h \leq \sqrt{2} \left(\|w_{x_1}\|_h^2 + \|w_{x_2}\|_h^2 \right)^{1/2} \leq \sqrt{2} \|\Delta w\|_h^{1/2} \|w\|_h^{1/2}.$$

Hence, the Cauchy inequality $ab \leq \epsilon a^2 + (4\epsilon)^{-1} b^2$, $\epsilon > 0$, gives

$$\|w_{x_1}\|_h + \|w_{x_2}\|_h \leq \epsilon \|\Delta w\|_h + (2\epsilon)^{-1} \|w\|_h.$$

Applying the triangle inequality to bound $\|\Delta w\|_h$ and using (6.15), we obtain

$$(6.20) \quad \|w_{x_1}\|_h + \|w_{x_2}\|_h \leq \sqrt{2} \epsilon |w|_{2,h} + (2\epsilon)^{-1} \|w\|_h.$$

Thus, from (6.18), (6.19), and (6.20), we have

$$(6.21) \quad \|\Phi\|_h \leq \|L_{\tilde{v}_h} w\|_h + C \mu_v (1 + \lambda_v) \left[\epsilon |w|_{2,h} + (\epsilon^{-1} + 1) \|w\|_h \right].$$

Multiplying (6.21) by $\sqrt{2} \nu^{-2} \mu_v$ and setting $\epsilon = \nu^2 (2\sqrt{2} C \mu_v^2 (1 + \lambda_v))^{-1}$, we obtain

$$(6.22) \quad \sqrt{2} \nu^{-2} \mu_v \|\Phi\|_h \leq \sqrt{2} \nu^{-2} \mu_v \|L_{\tilde{v}_h} w\|_h + (1/2) |w|_{2,h} + M \|w\|_h,$$

where

$$(6.23) \quad M \equiv \sqrt{2} C \nu^{-2} \mu_v^2 (1 + \lambda_v) \left[2\sqrt{2} C \nu^{-2} \mu_v^2 (1 + \lambda_v) + 1 \right].$$

Combining (6.17) and (6.22), we get

$$(6.24) \quad (1/2) |w|_{2,h} \leq \sqrt{2} \nu^{-2} \mu_v \|L_{\tilde{v}_h} w\|_h + M \|w\|_h.$$

It follows from (2.2) with $\zeta_1 = 1$, $\zeta_2 = 0$, $s = (t, t, t)$, and (2.3a) for $i = j = 1$ and $m + |\beta| = 0$ that $\nu \leq a_{11}(x, t, t, t) \leq \tilde{\mu}(t, t, t)$ for any $x \in \bar{\Omega}$ and $t \geq 0$ which, along with (2.4), implies $\bar{\mu}(t) \geq \nu$ for all $t \geq 0$. Therefore, by (6.10) and $b_{ii} \geq \nu$, we have $\nu \leq \mu_v$, and hence (6.23) gives

$$(6.25) \quad M \leq C \nu^{-4} \mu_v^2 (\mu_v^2 + \nu^2) (1 + \lambda_v)^2 \leq C \nu^{-4} \mu_v^4 (1 + \lambda_v)^2.$$

Using the inequality

$$\|z\|_{H^2(\Omega)}^2 \leq C \sum_{i=1}^2 \|z_{x_i x_i}\|_h^2, \quad z \in \mathcal{M}_h^0,$$

which is (2.7) in [2], (6.14), (6.24), and (6.25), we obtain

$$(6.26) \quad \|w\|_{H^2(\Omega)} \leq C \nu^{-2} \mu_v \|L_{\tilde{v}_h} w\|_h + C \nu^{-4} \mu_v^4 (1 + \lambda_v)^2 \|w\|_h.$$

Finally, (6.1) follows from (6.26), (5.2), and the inequality $\|w\|_h \leq C \|w\|_{L^2(\Omega)}$ (see [1, Lemma B.2]). \square

6.2. Second auxiliary inequality. To obtain the second auxiliary inequality, we introduce a formal adjoint of the linear differential operator L_v given by (2.5) and (2.6). For sufficiently smooth v defined on Ω , let

$$(6.27) \quad L_v^* \varphi(x) = \sum_{i,j=1}^2 [\tilde{a}_{ij}(x) \varphi]_{x_j x_i} - \sum_{k=0}^2 [A_v^k(x) \varphi]_{x_k}, \quad x \in \Omega,$$

where

$$(6.28) \quad \tilde{a}_{ij}(x) \equiv a_{ij}(x, v(x), \nabla v(x)), \quad i, j = 1, 2,$$

and A_v^k is given by (2.6). Assume that $v \in H^4(\Omega)$ and that a_{ij} and a are twice continuously differentiable on $\bar{\Omega} \times R^3$. Then $\tilde{a}_{ij} \in C^1(\bar{\Omega}) \cap H^2(\Omega)$ and $A_v^k \in C(\bar{\Omega}) \cap H^1(\Omega)$. Hence, using (2.1), L_v^* can be written in the form

$$L_v^* \varphi(x) = \sum_{i,j=1}^2 \tilde{a}_{ij}(x) \varphi_{x_i x_j} + \sum_{k=0}^2 \tilde{a}_k(x) \varphi_{x_k}, \quad x \in \Omega,$$

for some $\tilde{a}_k \in C(\bar{\Omega})$, $k = 1, 2$, and $\tilde{a}_0 \in L^2(\bar{\Omega})$. It follows from (6.28) and (2.2) that L_v^* is uniformly elliptic. Introducing the normed space

$$H^{2,0}(\Omega) = \{v \in H^2(\Omega) : v|_{\partial\Omega} = 0\}$$

with the $\|\cdot\|_{H^{2,0}(\Omega)}$ -norm, we see that L_v^* is a linear operator from $H^{2,0}(\Omega)$ into $L^2(\Omega)$. Moreover, L_v^* is a formal adjoint of L_v , that is,

$$(6.29) \quad \int_{\Omega} (L_v^* \varphi) w \, dx = \int_{\Omega} \varphi L_v w \, dx, \quad \varphi, w \in H^{2,0}(\Omega).$$

Indeed, for any φ and $w \in H^{2,0}(\Omega)$, the traces of φ_{x_i} , w_{x_i} , $i = 1, 2$, on $\partial\Omega$ are in $L^2(\partial\Omega)$. Hence, using Green's formula (see [8, equation (1.2.4)]) and $w = \varphi = 0$ on $\partial\Omega$, we obtain

$$(6.30) \quad \int_{\Omega} [\tilde{a}_{ij}(x) \varphi]_{x_j x_i} w \, dx = \int_{\Omega} \varphi \tilde{a}_{ij}(x) w_{x_i x_j} \, dx, \quad 1 \leq i, j \leq 2.$$

Similarly,

$$(6.31) \quad - \int_{\Omega} [A_v^k(x) \varphi]_{x_k} w \, dx = \int_{\Omega} \varphi A_v^k(x) w_{x_k} \, dx, \quad k = 1, 2.$$

Therefore, using (6.27), (6.30), (6.31), (6.28), and (2.5), we have (6.29).

The proof of the second auxiliary inequality is based on the following result.

LEMMA 6.2 (see [1, Lemma C.3]). *For l a positive integer, suppose that $g(x, s)$ is l -times continuously differentiable on $\Omega \times R^3$ and*

$$(6.32) \quad \left| \frac{\partial^{m+|\beta|} g}{\partial x_i^m \partial s^\beta}(x, s) \right| \leq \tilde{\sigma}(|s_0|, |s_1|, |s_2|), \quad m+|\beta| \leq l, \quad i = 1, 2, \quad (x, s) \in \Omega \times R^3,$$

where $\tilde{\sigma}(t_0, t_1, t_2)$, $t_0, t_1, t_2 \geq 0$, is continuous and nondecreasing in each variable. Then, for $g_w(x) = g(x, w(x))$, $\nabla w(x)$, $x \in \Omega$, we have

$$(6.33) \quad \left\| \frac{\partial^l g_w}{\partial x_i^l} \right\|_{C(\tau)} \leq C h^{1-l} \bar{\sigma}(\|w\|_{C^1(\tau)}) (1 + \|w\|_{C^2(\tau)}^l), \quad i = 1, 2, \quad w \in \mathcal{P}_h, \quad \tau \in \mathcal{T}_h,$$

where $\bar{\sigma}(t) = \tilde{\sigma}(t, t, t)$, $t \geq 0$, and C is independent of g and w .

In the proof of the second auxiliary inequality, we also use the following inverse inequalities: for $\tau \in \mathcal{T}_h$, $z \in \mathcal{P}_h$, and $i = 1, 2$,

$$(6.34) \quad \|z_{x_i}\|_{L^2(\tau)} \leq C h^{-1} \|z\|_{L^2(\tau)},$$

$$(6.35) \quad \|z_{x_i}\|_{C(\tau)} \leq C h^{-1} \|z\|_{C(\tau)}$$

(see [8, Theorem 3.2.6, equation (3.2.33)]).

The second auxiliary inequality is formulated in the following lemma.

LEMMA 6.3. *Suppose that (2.3a) holds for $0 \leq m \leq 4$ and all β such that $m + |\beta| \leq 5$, and that (2.3b) holds for $0 \leq m \leq 4$ and all β such that $m + |\beta| \leq 5$ and $|\beta| \geq 1$. Suppose that $v \in H^4(\Omega)$ and that the operator L_v^* of (6.27) is from $H^{2,0}(\Omega)$ onto $L^2(\Omega)$, has a bounded inverse, and $C_v = \|(L_v^*)^{-1}\|$. Then, for any $h \in (0, e^{-2}]$,*

$$(6.36) \quad \|w\|_{L^2(\Omega)} \leq C C_v \|L_{h, \tilde{v}_h} w\|_h + h C C_v \bar{\mu}(C \lambda_v) (1 + \lambda_v^5) \|w\|_{H^2(\Omega)}, \quad w \in \mathcal{M}_h^0.$$

Proof. We adapt the approach used in the proof of Lemma 3.2 of [2]. First, we observe that L_v^* is well defined since $v \in H^4(\Omega)$. Next we take any $w \in \mathcal{M}_h^0$. Since $\mathcal{M}_h^0 \subset L^2(\Omega)$ and L_v^* has a bounded inverse, there is unique $\varphi \in H^{2,0}(\Omega)$ such that

$$(6.37) \quad L_v^* \varphi = w,$$

$$(6.38) \quad \|\varphi\|_{H^2(\Omega)} \leq C_v \|w\|_{L^2(\Omega)}.$$

Let $\bar{\varphi}_h$ be the piecewise constant interpolant of φ such that

$$(6.39) \quad \|\varphi - \bar{\varphi}_h\|_{L^2(\Omega)} \leq C h \|\varphi\|_{H^1(\Omega)}.$$

Using (6.39) and (6.38), we obtain

$$(6.40) \quad \|\varphi - \bar{\varphi}_h\|_{L^2(\Omega)} \leq C C_v h \|w\|_{L^2(\Omega)}.$$

Also, using the exactness property of Gauss quadrature for a piecewise constant function, the triangle inequality, (6.40), and (6.38), we have

$$(6.41) \quad \|\bar{\varphi}_h\|_h = \|\bar{\varphi}_h\|_{L^2(\Omega)} \leq \|\varphi - \bar{\varphi}_h\|_{L^2(\Omega)} + \|\varphi\|_{L^2(\Omega)} \leq C C_v \|w\|_{L^2(\Omega)}.$$

As in Nitsche's trick [17], using (6.37) and (6.29), we obtain

$$(6.42) \quad \|w\|_{L^2(\Omega)}^2 = \int_\Omega w^2 dx = \int_\Omega (L_v^* \varphi) w dx = \int_\Omega \varphi L_v w dx = \sum_{i=1}^4 J_i,$$

where

$$\begin{aligned}
 J_1 &\equiv \int_{\Omega} (\varphi - \bar{\varphi}_h) L_v w \, dx, & J_2 &\equiv \int_{\Omega} \bar{\varphi}_h (L_v w - L_{\bar{v}_h} w) \, dx, \\
 J_3 &\equiv \int_{\Omega} \bar{\varphi}_h L_{\bar{v}_h} w \, dx - \sum_h \bar{\varphi}_h L_{\bar{v}_h} w, & J_4 &\equiv \sum_h \bar{\varphi}_h L_{\bar{v}_h} w.
 \end{aligned}$$

The Cauchy–Schwarz inequality, (6.40), and the estimate

$$\|L_v w\|_{L^2(\Omega)} \leq C \bar{\mu}(C \lambda_v) (1 + \lambda_v) \|w\|_{H^2(\Omega)}$$

(see [1, Lemma 7.2]) give

$$\begin{aligned}
 (6.43) \quad J_1 &\leq \left| \int_{\Omega} (\varphi - \bar{\varphi}_h) L_v w \, dx \right| \leq \|\varphi - \bar{\varphi}_h\|_{L^2(\Omega)} \|L_v w\|_{L^2(\Omega)}, \\
 &\leq C C_v h \bar{\mu}(C \lambda_v) (1 + \lambda_v) \|w\|_{H^2(\Omega)} \|w\|_{L^2(\Omega)}.
 \end{aligned}$$

The Cauchy–Schwarz inequality, (6.41), and the inequality

$$\|(L_v - L_{\bar{v}_h}) w\|_{L^2(\Omega)} \leq C h \bar{\mu}(C \lambda_v) \lambda_v (1 + \lambda_v) \|w\|_{H^2(\Omega)}$$

(see [1, Lemma 7.2]) give

$$\begin{aligned}
 (6.44) \quad J_2 &\leq \left| \int_{\Omega} \bar{\varphi}_h (L_v w - L_{\bar{v}_h} w) \, dx \right| \leq \|\bar{\varphi}_h\|_{L^2(\Omega)} \|(L_v - L_{\bar{v}_h}) w\|_{L^2(\Omega)} \\
 &\leq C C_v h \bar{\mu}(C \lambda_v) \lambda_v (1 + \lambda_v) \|w\|_{H^2(\Omega)} \|w\|_{L^2(\Omega)}.
 \end{aligned}$$

The Cauchy–Schwarz inequality in \mathcal{M}_h^0 , (6.41), and (5.2) give

$$(6.45) \quad J_4 \leq \|\bar{\varphi}_h\|_h \|L_{\bar{v}_h} w\|_h \leq C C_v \|w\|_{L^2(\Omega)} \|L_{\bar{v}_h} w\|_h \leq C C_v \|L_{h, \bar{v}_h} w\|_h \|w\|_{L^2(\Omega)}.$$

Suppose that

$$(6.46) \quad J_3 \leq C C_v h \bar{\mu}(C \lambda_v) (1 + \lambda_v^5) \|w\|_{H^2(\Omega)} \|w\|_{L^2(\Omega)}.$$

Then, using (6.42)–(6.46) and

$$(6.47) \quad t^p \leq t^q + 1, \quad t \geq 0, \quad 0 < p \leq q,$$

we obtain (6.36).

It remains to prove (6.46). Using the triangle inequality and setting $g(x) = \bar{\varphi}_h(x) L_{\bar{v}_h} w(x)$, we get

$$\begin{aligned}
 (6.48) \quad J_3 &\leq \left| \int_{\Omega} \bar{\varphi}_h L_{\bar{v}_h} w \, dx - \sum_h \bar{\varphi}_h L_{\bar{v}_h} w \right| \leq \sum_{\tau \in \mathcal{T}_h} \left| \int_{\tau} g(x) \, dx - \frac{1}{4} \text{mes}(\tau) \sum_{x \in \tau \cap \mathcal{G}_h} g(x) \right|.
 \end{aligned}$$

We fix $\tau = (x_1^{k_1-1}, x_1^{k_1}) \times (x_2^{k_2-1}, x_2^{k_2}) \in \mathcal{T}_h$. For η_1 and η_2 given in (2.8) and $\zeta = (\zeta_1, \zeta_2) \in \Omega$, we introduce the linear functional

$$F(z) = \int_{\Omega} z(\zeta) \, d\zeta - \frac{1}{4} \sum_{l_1, l_2=1}^2 z(\eta_{l_1}, \eta_{l_2}), \quad z \in H_1^4(\Omega).$$

Making a change of variables, we obtain

$$(6.49) \quad \int_{\tau} g(x) \, dx - \frac{1}{4} h_1^{k_1} h_2^{k_2} \sum_{x \in \tau \cap \mathcal{G}_h} g(x) = h_1^{k_1} h_2^{k_2} F(\tilde{g}),$$

where $\tilde{g}(\zeta) = g(x_1^{k_1-1} + h_1^{k_1} \zeta_1, x_2^{k_2-1} + h_2^{k_2} \zeta_2)$. Since $\tilde{g} \in H_1^4(\Omega)$, $|F(z)| \leq C \|z\|_{H_1^4(\Omega)}$, $z \in H_1^4(\Omega)$, and $F(p) = 0$, $p \in P_3 \otimes P_3$, it follows from the Bramble–Hilbert lemma [7, Theorem 2] that

$$(6.50) \quad |F(\tilde{g})| \leq C \int_{\Omega} \left(\left| \frac{\partial^4 \tilde{g}}{\partial \zeta_1^4} \right| + \left| \frac{\partial^4 \tilde{g}}{\partial \zeta_2^4} \right| \right) d\zeta.$$

Using (6.48)–(6.50), making a change of variables, and taking into account the fact that $\bar{\varphi}_h|_{\tau}$ is a constant for any $\tau \in \mathcal{T}_h$, we have

$$J_3 \leq C h^4 \sum_{k=1}^2 \sum_{\tau \in \mathcal{T}_h} \int_{\tau} |\bar{\varphi}_h \partial_k^4 L_{\tilde{v}_h} w| \, dx,$$

where $\partial_k^l = \partial^l / \partial x_k^l$. Applying the Cauchy–Schwarz inequality in $L^2(\tau)$ and in $R^{N_1 N_2}$ and using (6.41), we get

$$(6.51) \quad \begin{aligned} J_3 &\leq C h^4 \sum_{k=1}^2 \sum_{\tau \in \mathcal{T}_h} \|\bar{\varphi}_h\|_{L^2(\tau)} \|\partial_k^4 L_{\tilde{v}_h} w\|_{L^2(\tau)} \\ &\leq C C_v h^4 \|w\|_{L^2(\Omega)} \sum_{k=1}^2 \sqrt{\sum_{\tau \in \mathcal{T}_h} \|\partial_k^4 L_{\tilde{v}_h} w\|_{L^2(\tau)}^2}. \end{aligned}$$

Using (2.5), (2.6), and the triangle inequality, we obtain

$$(6.52) \quad \|\partial_k^4 L_{\tilde{v}_h} w\|_{L^2(\tau)} \leq \sum_{i,j=1}^2 P_{k,\tau}^{(i,j)} + \sum_{\nu=0}^2 \sum_{i,j=1}^2 Q_{\nu,k,\tau}^{(i,j)} + \sum_{\nu=0}^2 R_{\nu,k,\tau},$$

where, for $\tau \in \mathcal{T}_h$, $i, j, k = 1, 2$, and $0 \leq \nu \leq 2$,

$$(6.53) \quad P_{k,\tau}^{(i,j)} = \left\| \partial_k^4 [a_{ij}(\cdot, \tilde{v}_h, \nabla \tilde{v}_h) w_{x_i x_j}] \right\|_{L^2(\tau)},$$

$$(6.54) \quad Q_{\nu,k,\tau}^{(i,j)} = \left\| \partial_k^4 \left[\frac{\partial a_{ij}}{\partial s_{\nu}}(\cdot, \tilde{v}_h, \nabla \tilde{v}_h) (\tilde{v}_h)_{x_i x_j} w_{x_{\nu}} \right] \right\|_{L^2(\tau)},$$

$$(6.55) \quad R_{\nu,k,\tau} = \left\| \partial_k^4 \left[\frac{\partial a}{\partial s_{\nu}}(\cdot, \tilde{v}_h, \nabla \tilde{v}_h) w_{x_{\nu}} \right] \right\|_{L^2(\tau)}.$$

Next we estimate the terms in (6.53)–(6.55). We fix $i, j, k = 1, 2$, $\tau \in \mathcal{T}_h$ and bound $P_{k,\tau}^{(i,j)}$. Using Leibniz’s formula, for any $x \in \tau$, we have

$$(6.56) \quad \partial_k^4 [a_{ij}(x, \tilde{v}_h, \nabla \tilde{v}_h) w_{x_i x_j}] = \sum_{l=0}^4 C_4^l [\partial_k^l a_{ij}(x, \tilde{v}_h, \nabla \tilde{v}_h)] \partial_k^{4-l} w_{x_i x_j},$$

where $C_n^m = n! / (m!(n-m)!)$. Since w is a bicubic polynomial on τ , the term in (6.56) corresponding to $l = 0$ is 0. Using (6.53), (6.56), and the triangle inequality, we get

$$(6.57) \quad P_{k,\tau}^{(i,j)} \leq C \sum_{l=1}^4 \|\partial_k^l a_{ij}(\cdot, \tilde{v}_h, \nabla \tilde{v}_h)\|_{C(\tau)} \|\partial_k^{4-l} w_{x_i x_j}\|_{L^2(\tau)}.$$

We apply Lemma 6.2 with $g = a_{ij}$, $1 \leq l \leq 4$, $\tilde{\sigma} = \tilde{\mu}$, and $w = \tilde{v}_h$. We note that (6.32) follows from condition (2.3a) for all m and β such that $m + |\beta| \leq 4$. Therefore, using (6.33) and (2.4), we have

$$\|\partial_k^l a_{ij}(\cdot, \tilde{v}_h, \nabla \tilde{v}_h)\|_{C(\tau)} \leq C h^{1-l} \bar{\mu} (\|\tilde{v}_h\|_{C^1(\tau)}) [1 + \|\tilde{v}_h\|_{C^2(\tau)}^l], \quad 1 \leq l \leq 4.$$

Applying (2.9) and (6.47), we obtain

$$(6.58) \quad \|\partial_k^l a_{ij}(\cdot, \tilde{v}_h, \nabla \tilde{v}_h)\|_{C(\tau)} \leq C h^{1-l} \bar{\mu} (C \lambda_v) (1 + \lambda_v^4), \quad 1 \leq l \leq 4.$$

Using (6.34) $(4 - l)$ -times, we get

$$(6.59) \quad \|\partial_k^{4-l} w_{x_i x_j}\|_{L^2(\tau)} \leq C h^{l-4} \|w_{x_i x_j}\|_{L^2(\tau)}, \quad 1 \leq l \leq 4.$$

Thus, from (6.57)–(6.59), we have

$$(6.60) \quad P_{k,\tau}^{(ij)} \leq C h^{-3} \bar{\mu} (C \lambda_v) (1 + \lambda_v^4) \|w\|_{H^2(\tau)}, \quad i, j, k = 1, 2, \quad \tau \in \mathcal{T}_h.$$

We fix $i, j, k = 1, 2$, $0 \leq \nu \leq 2$, $\tau \in \mathcal{T}_h$ and bound $Q_{\nu,k,\tau}^{(ij)}$ given by (6.54). Applying Leibniz’s formula twice and taking into account the fact that w and \tilde{v}_h are bicubic polynomials on τ , we have

$$(6.61) \quad \begin{aligned} & \partial_k^4 \left(\frac{\partial a_{ij}}{\partial s_\nu}(x, \tilde{v}_h, \nabla \tilde{v}_h) (\tilde{v}_h)_{x_i x_j} w_{x_\nu} \right) \\ &= \sum_{n=1}^4 \sum_{l=1}^n C_4^n C_n^l \left(\partial_k^l \frac{\partial a_{ij}}{\partial s_\nu}(x, \tilde{v}_h, \nabla \tilde{v}_h) \right) [\partial_k^{n-l} (\tilde{v}_h)_{x_i x_j}] \partial_k^{4-n} w_{x_\nu} \\ & \quad + \sum_{n=1}^3 C_4^n C_n^0 \frac{\partial a_{ij}}{\partial s_\nu}(x, \tilde{v}_h, \nabla \tilde{v}_h) [\partial_k^n (\tilde{v}_h)_{x_i x_j}] \partial_k^{4-n} w_{x_\nu}. \end{aligned}$$

Using (6.54), (6.61), and the triangle inequality, we obtain

$$(6.62) \quad Q_{\nu,k,\tau}^{(ij)} \leq C (T_1 + T_2),$$

where

$$\begin{aligned} T_1 &\equiv \sum_{n=1}^4 \sum_{l=1}^n \left\| \partial_k^l \frac{\partial a_{ij}}{\partial s_\nu}(\cdot, \tilde{v}_h, \nabla \tilde{v}_h) \right\|_{C(\tau)} \|\partial_k^{n-l} (\tilde{v}_h)_{x_i x_j}\|_{C(\tau)} \|\partial_k^{4-n} w_{x_\nu}\|_{L^2(\tau)}, \\ T_2 &\equiv \sum_{n=1}^3 \left\| \frac{\partial a_{ij}}{\partial s_\nu}(\cdot, \tilde{v}_h, \nabla \tilde{v}_h) \right\|_{C(\tau)} \|\partial_k^n (\tilde{v}_h)_{x_i x_j}\|_{C(\tau)} \|\partial_k^{4-n} w_{x_\nu}\|_{L^2(\tau)}. \end{aligned}$$

First we bound T_1 . We apply Lemma 6.2 with $1 \leq l \leq 4$, $g = \partial a_{ij}/\partial s_\nu$, $\tilde{\sigma} = \tilde{\mu}$, and $w = \tilde{v}_h$. We note that (6.32) follows from condition (2.3a) for all m and β such that $m + |\beta| \leq 5$, $0 \leq m \leq 4$, and $|\beta| \geq 1$. Therefore, using (6.33), (2.4), (2.9), and (6.47), we have

$$(6.63) \quad \left\| \partial_k^l \frac{\partial a_{ij}}{\partial s_\nu}(\cdot, \tilde{v}_h, \nabla \tilde{v}_h) \right\|_{C(\tau)} \leq C h^{1-l} \bar{\mu} (C \lambda_v) (1 + \lambda_v^4), \quad 1 \leq l \leq 4.$$

For $1 \leq n \leq 4$ and $1 \leq l \leq n$, using (6.35) $(n - l)$ -times and (2.9), we get

$$(6.64) \quad \|\partial_k^{n-l} (\tilde{v}_h)_{x_i x_j}\|_{C(\tau)} \leq C h^{l-n} \|(\tilde{v}_h)_{x_i x_j}\|_{C(\tau)} \leq C h^{l-n} \lambda_v.$$

We note that (6.64) also holds for $l = 0$. For $1 \leq n \leq 4$, using (6.34) $(4 - n)$ -times, we obtain

$$(6.65) \quad \left\| \partial_k^{4-n} w_{x_\nu} \right\|_{L^2(\tau)} \leq C h^{n-4} \|w_{x_\nu}\|_{L^2(\tau)} \leq C h^{n-4} \|w\|_{H^1(\tau)}.$$

Inequalities (6.63)–(6.65) imply that

$$(6.66) \quad T_1 \leq C h^{-3} \bar{\mu}(C \lambda_\nu) \lambda_\nu (1 + \lambda_\nu^4) \|w\|_{H^1(\tau)}.$$

Next we estimate T_2 . Using (2.3a) for $m = 0$ and $|\beta| = 1$, (2.9), and (2.4), we get

$$(6.67) \quad \left\| \frac{\partial a_{ij}}{\partial s_\nu}(\cdot, \tilde{v}_h, \nabla \tilde{v}_h) \right\|_{C(\tau)} \leq \tilde{\mu} (\|\tilde{v}_h\|_{C(\tau)}, \|(\tilde{v}_h)_{x_1}\|_{C(\tau)}, \|(\tilde{v}_h)_{x_2}\|_{C(\tau)}) \leq \bar{\mu}(C \lambda_\nu).$$

For $1 \leq n \leq 3$, using (6.34) $(3 - n)$ -times, we have

$$(6.68) \quad \left\| \partial_k^{4-n} w_{x_\nu} \right\|_{L^2(\tau)} \leq C h^{n-3} \|w_{x_\nu x_k}\|_{L^2(\tau)}.$$

Using (6.67), (6.68), and (6.64) for $l = 0$ and $1 \leq n \leq 3$, we obtain

$$(6.69) \quad T_2 \leq C h^{-3} \bar{\mu}(C \lambda_\nu) \lambda_\nu \|w\|_{H^2(\tau)}.$$

Thus, from (6.62), (6.66), and (6.69), we have, for any $\tau \in \mathcal{T}_h$,

$$(6.70) \quad Q_{\nu,k,\tau}^{(ij)} \leq C h^{-3} \bar{\mu}(C \lambda_\nu) \lambda_\nu (1 + \lambda_\nu^4) \|w\|_{H^2(\tau)}, \quad i, j, k = 1, 2, \nu = 0, 1, 2.$$

Bounding $R_{\nu,k,\tau}$ of (6.55) in a way similar to that of $P_{k,\tau}^{(i,j)}$, for any $\tau \in \mathcal{T}_h$, we obtain

$$(6.71) \quad R_{\nu,k,\tau} \leq C h^{-3} \bar{\mu}(C \lambda_\nu) (1 + \lambda_\nu^4) \|w\|_{H^1(\tau)}, \quad k = 1, 2, \quad \nu = 0, 1, 2.$$

Thus, from (6.52), (6.60), (6.70), and (6.71), we get

$$(6.72) \quad \left\| \partial_k^4 L_{\tilde{v}_h} w \right\|_{L^2(\tau)} \leq C h^{-3} \bar{\mu}(C \lambda_\nu) (1 + \lambda_\nu) (1 + \lambda_\nu^4) \|w\|_{H^2(\tau)}.$$

Finally, (6.46) follows from (6.51), (6.72), (6.47), and $\mathcal{M}_h^0 \subset H^2(\Omega)$. \square

6.3. Bound on the inverse of the Fréchet derivative. Using the first and the second auxiliary inequalities, we obtain a bound on $\|L_{h,\tilde{v}_h}^{-1}\|$ for $v \in H^4(\Omega)$.

LEMMA 6.4. *Under the conditions of Lemma 6.3, there exist positive constants $h_0 \leq e^{-2}$ and K_1 , both depending on $\|v\|_{H^4(\Omega)}$, such that, for any $h \in (0, h_0]$, L_{h,\tilde{v}_h}^{-1} exists, and $\|L_{h,\tilde{v}_h}^{-1}\| \leq K_1$.*

Proof. Substituting (6.36) into (6.1), we obtain

$$(6.73) \quad \|w\|_{H^2(\Omega)} \leq (K_1/2) \|L_{h,\tilde{v}_h} w\|_h + h M \|w\|_{H^2(\Omega)}, \quad w \in \mathcal{M}_h^0,$$

for some positive constants K_1 and M which depend on λ_ν and ν but are independent of h . Setting $h_0 = \min \{e^{-2}, (2M)^{-1}\}$, we have

$$\|w\|_{H^2(\Omega)} \leq K_1 \|L_{h,\tilde{v}_h} w\|_h, \quad w \in \mathcal{M}_h^0, \quad h \in (0, h_0],$$

which implies that the linear operator L_{h,\tilde{v}_h} has an inverse, and $\|L_{h,\tilde{v}_h}^{-1}\| \leq K_1$. \square

7. Existence, uniqueness, and error estimates. Let L be given by (1.2), and L_v^* be given by (6.27), (6.28), and (2.6). Let u be a solution of (1.1).

THEOREM 7.1. *Suppose that (2.3a) holds for $0 \leq m \leq 4$ and all β such that $m + |\beta| \leq 5$, that (2.3b) holds for $0 \leq m \leq 4$ and all β such that $m + |\beta| \leq 5$ and $|\beta| \geq 1$, and that*

$$(7.1) \quad \tilde{\mu}(t_0, t_1, t_2) = \mu(t_0)(1 + t_1^q + t_2^q), \quad q \geq 0,$$

where μ is a continuous, positive, and nondecreasing function. Let $u \in H^k(\Omega)$, $k = 4, 5$, and suppose that operator L_u^* is from $H^{2,0}(\Omega)$ onto $L^2(\Omega)$ and has a bounded inverse. Then there exist positive constants h_* , C_1 , C_2 , and M that depend on $\|u\|_{H^k(\Omega)}$ such that, for any $h \in (0, h_*)$ and

$$(7.2) \quad \rho = |\ln h|^{-2}(C_1 + C_2|\ln h|^q)^{-1},$$

the OSC problem (3.3) has a unique solution $u_h \in B_h(\tilde{u}_h, \rho)$, and

$$(7.3) \quad \|u - u_h\|_{H^{6-k}(\Omega)} \leq M h^{k-2}.$$

Proof. Lemma 4.1 with $v = u$ implies

$$(7.4) \quad \|Lu - L_h \tilde{u}_h\|_h \leq K_3 h^{k-2},$$

where $K_3 \geq 0$ is independent of h but depends on $\|u\|_{H^k(\Omega)}$. From Lemma 5.1 with $v = u$ and $\rho_0 = 1$ and (7.1), it follows that, for $h \in (0, e^{-2}]$, operator L_h has a Fréchet derivative $L_{h,y}$ for any $y \in \mathcal{M}_h^0$, and

$$(7.5) \quad \|L_{h,z} - L_{h,y}\| \leq K_2(h) \|z - y\|_{H^2(\Omega)}, \quad y, z \in B_h(\tilde{u}_h, 1),$$

where

$$(7.6) \quad K_2(h) \equiv K_2(h, 1, u) = (C + \gamma)\mu(\gamma)(\ln^2 h)(1 + 2(\gamma|\ln h|^q)),$$

and $\gamma = C(\|u\|_{H^4(\Omega)} + 1)$. We conclude from Lemma 6.4 with $v = u$ that there exist positive constants $h_0 \leq e^{-2}$ and K_1 , both depending on $\|u\|_{H^4(\Omega)}$, such that, for any $h \in (0, h_0]$, L_{h,\tilde{u}_h}^{-1} exists, and (3.4) holds.

Since $\mu(\gamma) > 0$ and $q \geq 0$, it follows from (7.6) that $K_2(h) \rightarrow \infty$ as $h \rightarrow 0$. Hence, there exists $h_1 \in (0, e^{-2}]$ such that

$$(7.7) \quad [2K_1 K_2(h)]^{-1} \leq 1, \quad h \in (0, h_1].$$

Next we prove that there exists $h_2 \in (0, e^{-2}]$ such that

$$(7.8) \quad K_1 K_3 h^{k-2} \leq [4K_1 K_2(h)]^{-1}, \quad h \in (0, h_2].$$

We take any $h \in (0, e^{-2}]$ and set $t = \gamma|\ln h|$. Using $h^{k-2} = e^{-(k-2)t/\gamma}$, (7.6), and $\ln^2 h = (t/\gamma)^2$, we see that the inequality in (7.8) is equivalent to

$$(7.9) \quad t^2 + 2t^{2+q} \leq \gamma^2 (4K_1^2 K_3 (C + \gamma)\mu(\gamma))^{-1} e^{(k-2)t/\gamma}.$$

Clearly there exists $t_* > 0$ such that (7.9) holds for all $t \geq t_*$. Therefore we conclude that (7.8) holds with $h_2 = \min\{e^{-t_*/\gamma}, e^{-2}\}$.

We set $h_* = \min \{h_0, h_1, h_2\}$ and

$$(7.10) \quad \rho = [2 K_1 K_2(h)]^{-1}, \quad h \in (0, h_*].$$

Using (7.10) and (7.6), for $h \in (0, h_*]$, it is easy to obtain (7.2) with $C_1 = 2K_1(C + \gamma)\mu(\gamma)$ and $C_2 = 2\gamma^q C_1$.

We fix any $h \in (0, h_*]$ and consider ρ given by (7.10). We have proved that the operator L_h has a Fréchet derivative $L_{h,y}$ for any $y \in \mathcal{M}_h^0$, L_{h,\tilde{u}_h}^{-1} exists and (3.4) holds. It follows from (7.10) and (7.7) that $\rho \leq 1$. Hence, (7.5) implies (3.5), and (7.4) implies (3.6) with $p = k - 2$. Finally, (7.10) and (7.8) imply (3.7) and (3.8) with $p = k - 2$. Thus it follows from Theorem 3.1 that (3.3) has a unique solution $u_h \in B_h(\tilde{u}_h, \rho)$. Moreover, using the triangle inequality, (2.10) and (3.9) with $p = k - 2$, we obtain

$$\|u - u_h\|_{H^{6-k}(\Omega)} \leq \|u - \tilde{u}_h\|_{H^{6-k}(\Omega)} + \|\tilde{u}_h - u_h\|_{H^2(\Omega)} \leq (C \|u\|_{H^4(\Omega)} + 2K_1 K_3) h^{k-2},$$

which gives (7.3) with M depending on $\|u\|_{H^k(\Omega)}$. \square

In (7.3), the H^2 error estimate is optimal, whereas the H^1 error estimate has optimal order.

COROLLARY 7.1. *Under the conditions of Theorem 7.1, there exists $h_{**} > 0$ such that, for any $h \in (0, h_{**}]$, L_{h,\tilde{u}_h}^{-1} exists and (3.4) holds with $K_1 > 0$ independent of h , L_h has a Fréchet derivative $L_{h,y}$ for any $y \in \mathcal{M}_h^0$, (3.5) holds with $\rho = [2 K_1 K_2(h)]^{-1}$ and $K_2 = K_2(h)$ given by (7.6), and the OSC problem (3.3) has a unique solution $u_h \in B_h(\tilde{u}_h, \rho/2)$.*

8. Newton’s method. Newton’s method for the iterative solution of (3.3) is formulated as follows. Given $u_0 \in \mathcal{M}_h^0$, compute u_{k+1} from

$$(8.1) \quad L_{h,u_k}(u_{k+1} - u_k) = -(L_h u_k - f_h), \quad k = 0, 1, \dots$$

THEOREM 8.1. *Suppose that the conditions of Theorem 7.1 hold, and let h_{**} , K_1 , $K_2(h)$, ρ , and u_h be as in Corollary 7.1. If $h \in (0, h_{**}]$ and $u_0 \in B_h(u_h, \rho/2)$, then Newton’s method (8.1) generates a sequence $\{u_k\}_{k=0}^\infty \subset B_h(u_h, \rho/2)$ and*

$$(8.2) \quad \|u_k - u_h\|_{H^2(\Omega)} \leq \rho (1/2)^{2^k - 1}, \quad k = 1, 2, \dots$$

Proof. We set $r = \rho/2$, $\kappa_1 = 2K_1$, $\kappa_2 = K_2(h)$, and take any $y \in B_h(u_h, r)$. According to Corollary 7.1, there exists L_{h,\tilde{u}_h}^{-1} , and (3.4) holds. Using (3.5), the triangle inequality, $u_h \in B_h(\tilde{u}_h, \rho/2)$, $y \in B_h(u_h, \rho/2)$, and $\rho = [2 K_1 K_2(h)]^{-1}$, we obtain

$$(8.3) \quad \begin{aligned} \|L_{h,\tilde{u}_h} - L_{h,y}\| &\leq K_2(h)(\|\tilde{u}_h - u_h\|_{H^2(\Omega)} + \|u_h - y\|_{H^2(\Omega)}) \\ &\leq K_2(h)\rho = 1/(2K_1), \end{aligned}$$

which implies $\|L_{h,\tilde{u}_h} - L_{h,y}\| < \|L_{h,\tilde{u}_h}^{-1}\|^{-1}$ by (3.4). Applying the generalization of Banach’s theorem [13, Ch. V, section 4, Theorem 4], we conclude that there exists $L_{h,y}^{-1}$ and

$$\|L_{h,y}^{-1}\| \leq \|L_{h,\tilde{u}_h}^{-1}\| / (1 - \|L_{h,\tilde{u}_h}^{-1}\| \|L_{h,y} - L_{h,\tilde{u}_h}\|),$$

which, along with (3.4) and (8.3), implies $\|L_{h,y}^{-1}\| \leq \kappa_1$ for all $y \in B_h(u_h, r)$.

Since $u_h \in B_h(\tilde{u}_h, \rho/2)$, we have $B_h(u_h, \rho/2) \subset B_h(\tilde{u}_h, \rho)$. By Corollary 7.1, L_h has a Fréchet derivative $L_{h,y}$ at any $y \in \mathcal{M}_h^0$, (3.5) holds, and

$$\|L_{h,z} - L_{h,y}\| \leq \kappa_2 \|z - y\|_{H^2(\Omega)}, \quad y, z \in B_h(u_h, r).$$

Using $\rho = [2K_1K_2(h)]^{-1} = (\kappa_1 \kappa_2)^{-1}$, we obtain $r = \rho/2 < (\kappa_1 \kappa_2)^{-1}$. Thus, using Theorem 9.1 in [1] which is a modification of Theorem 4 in [22, p. 359], we conclude that Newton's method (8.1) generates the sequence $\{u_k\}_{k=0}^\infty \subset B_h(u_h, \rho/2)$, and (8.2) holds. \square

It follows from (7.10) and the statement following the proof of Lemma 5.1 that ρ is independent of h if the coefficients a_{ij} of the differential operator L do not depend on ∇u .

9. Conclusions. We have shown that the nonlinear OSC problem (3.3) locally has a unique solution u_h with the same convergence properties as the solution of the corresponding linear OSC problem considered in [2]. That is, for both the linear and the nonlinear OSC solutions, we have an optimal H^2 error estimate, and an optimal order H^1 error estimate if $u \in H^5(\Omega)$. We have also shown that Newton's method converges quadratically provided that the initial approximation lies sufficiently close to the OSC solution.

Acknowledgment. The authors wish to thank Graeme Fairweather for his assistance during the preparation of this paper.

REFERENCES

- [1] R. AITBAYEV AND B. BIALECKI, *Orthogonal Spline Collocation for Nonlinear Dirichlet Problems*, Tech. Report MCS-99-01, Colorado School of Mines, Golden, CO, 1999.
- [2] B. BIALECKI, *Convergence analysis of orthogonal spline collocation for elliptic boundary value problems*, SIAM J. Numer. Anal., 35 (1998), pp. 617–631.
- [3] B. BIALECKI, *Superconvergence of the orthogonal spline collocation solution of Poisson's equation*, Numer. Methods Partial Differential Equations, 15 (1999), pp. 285–303.
- [4] B. BIALECKI AND X. CAI, *H^1 -norm error bounds for piecewise Hermite bicubic orthogonal spline collocation schemes for elliptic boundary value problems*, SIAM J. Numer. Anal., 31 (1994), pp. 1128–1146.
- [5] B. BIALECKI AND G. FAIRWEATHER, *Spline collocation methods for partial differential equations*, J. Comput. Appl. Math., to appear.
- [6] C. DE BOOR AND B. SWARTZ, *Collocation at Gaussian points*, SIAM J. Numer. Anal., 10 (1973), pp. 582–606.
- [7] J. BRAMBLE AND S. HILBERT, *Bounds for a class of linear functionals with applications to Hermite interpolation*, Numer. Math., 16 (1971), pp. 362–369.
- [8] P. G. CIARLET, *The Finite Element Method for Elliptic Problems*, North-Holland, Amsterdam, 1978.
- [9] J. DOUGLAS, JR. AND T. DUPONT, *Collocation Methods for Parabolic Equations in a Single Space Variable*, Lecture Notes in Math. 385, Springer-Verlag, New York, 1974.
- [10] J. DOUGLAS, JR. AND T. DUPONT, *A Galerkin method for a nonlinear Dirichlet problem*, Math. Comp., 29 (1975), pp. 689–696.
- [11] J. FREHSE AND R. RANNACHER, *Asymptotic L^∞ -error estimates for linear finite element approximations of quasilinear boundary value problems*, SIAM J. Numer. Anal., 15 (1978), pp. 418–431.
- [12] A. GRABARSKI, *The collocation method for the quasi-linear elliptic equation of second order*, Demonstratio Math., 19 (1986), pp. 431–447.
- [13] L. V. KANTOROVICH AND G. P. AKILOV, *Functional Analysis*, Pergamon Press, Oxford, 1982.
- [14] H. B. KELLER, *Approximation methods for nonlinear problems with application to two-point boundary value problem*, Math. Comp., 29 (1975), pp. 464–474.
- [15] M. A. KRASNOSEL'SKII, G. M. VAINIKKO, P. ZABREIKO, Y. B. RUTITSKII, AND V. Y. STETSENKO, *Approximate Solution of Operator Equations*, Wolters-Noordhoff, Groningen, Netherlands, 1972.

- [16] O. A. LADYZHENSKAJA AND N. N. URAL'CEVA, *Linear and Quasilinear Elliptic Equations*, Academic Press, New York, 1968.
- [17] J. A. NITSCHKE, *Ein Kriterium für die quasi-optimalität des Ritzschen verfahrens*, Numer. Math, 11 (1968), pp. 346–348.
- [18] J. M. ORTEGA AND W. C. RHEINBOLDT, *Iterative Solution of Nonlinear Equations in Several Variables*, Academic Press, New York, 1970.
- [19] E. J. PARK, *Mixed finite element methods for nonlinear second-order elliptic problems*, SIAM J. Numer. Anal., 32 (1995), pp. 865–885.
- [20] P. PERCELL AND M. F. WHEELER, *A C^1 finite element collocation method for elliptic equations*, SIAM J. Numer. Anal., 17 (1980), pp. 605–622.
- [21] P. M. PRENTER AND R. D. RUSSELL, *Orthogonal collocation for elliptic partial differential equations*, SIAM J. Numer. Anal., 13 (1976), pp. 923–939.
- [22] A. A. SAMARSKII AND E. NIKOLAEV, *Numerical Methods for Grid Equations, Iterative Methods*, Vol. II, Birkhäuser-Verlag, Basel, 1989.